# Tension/compression force transducer With thin-film technology and swivel head up to 45 kN Model F2303 

## Applications

- Machine building and plant construction
- Manufacturing automation
- Presses, lifting cylinders, welding guns, drives
- Chemistry and petrochemistry


## Special features

- Measuring ranges $0 \ldots 10 \mathrm{kN}$ to $0 \ldots 45 \mathrm{kN}$
[0 ... 2,248 Ibf to $0 \ldots 10,116 \mathrm{lbf}$ ]
■ Corrosion-resistant stainless steel design
- Integrated amplifier
- High long-term stability, high shock and vibration resistance

■ Good reproducibility, simple installation

## Description

The tension/compression force transducer is designed for static and dynamic measurement tasks in the direct flux of force. It determine the tension and compression forces in a wide scope of applications.

Force transducers of this model are used for measuring axial forces on electric spindle presses, for monitoring overload protection in lifting cylinders and for measuring force on punches, presses and welding guns.

Appropriate technical and regional approvals are available as an option.

The force transducer is made of high-strength, corrosion resistant stainless steel 1.4542 , which is particularly suitable for their application areas.

As output signals, the common active current and voltage outputs are available ( $4 \ldots 20 \mathrm{~mA}, 0 \ldots 10 \mathrm{~V}$ ). Also redundant output signals and CANopen ${ }^{\circledR}$ protocols are possible.

## Specifications in accordance with VDI/VDE/DKD 2638

| Model | F2303 |
| :---: | :---: |
| Rated force $\mathrm{F}_{\text {nom }} \mathbf{k N}$ | 10, 18, 20, 34, 45 |
| Rated force $\mathrm{F}_{\text {nom }}$ lbf | 2,248; 4,047; 4,496; 7,644; 10,116 |
| Relative linearity error $\mathrm{d}_{\text {lin }}{ }^{1}$ ) | 0.5 \% $\mathrm{F}_{\text {nom }}$ |
| Relative reversibility error | $<0.1 \% \mathrm{~F}_{\text {nom }}$ |
| Relative creep, 30 min . at $\mathrm{F}_{\text {nom }}$ | 0.1 \% F ${ }_{\text {nom }}$ |
| Temperature effect on |  |
| Zero signal TK0 | 0.2 \% $\mathrm{F}_{\text {nom }} / 10 \mathrm{~K}$ |
| Characteristic value TK $_{C}$ | 0.2 \% $F_{\text {nom }} / 10 \mathrm{~K}$ |
| Limit force $\mathrm{F}_{\mathrm{L}}$ | 150 \% $F_{\text {nom }}$ |
| Breaking force $F_{B}$ | $300 \% F_{\text {nom }}$ |
| Permissible vibration loading $\mathrm{F}_{\mathrm{rb}}$ | $50 \% \mathrm{~F}_{\text {nom }}$ (in accordance with DIN 50100) |
| Rated displacement (typical) $\mathbf{s}_{\text {nom }}$ | $<0.1 \mathrm{~mm}$ [<0.004 in] |
| Material of the measuring body | - Corrosion-resistant stainless steel 1.4542, ultrasound-tested 3,1 material <br> - Version with 3,2 material available |
| Rated temperature range $B_{T, ~ n o m}$ | $-20 \ldots+80^{\circ} \mathrm{C}\left[-4 \ldots+176^{\circ} \mathrm{F}\right]$ |
| Service temperature range $B_{T, G}$ | $-30 \ldots+80^{\circ} \mathrm{C}\left[-22 \ldots+176^{\circ} \mathrm{F}\right]$ |
| Storage temperature range $B_{T, S}$ | $-40 \ldots+85^{\circ} \mathrm{C}\left[-40 \ldots+185^{\circ} \mathrm{F}\right]$ |
| Electrical connection | Circular connector M12 x 1, 5-pin |
| Output signal <br> (Rated characteristic value) $\mathrm{C}_{\text {nom }}$ | - 4 ... 20 mA 2-wire <br> - $4 \ldots 20 \mathrm{~mA}$ 3-wire <br> - DC $0 \ldots 10 \mathrm{~V} 3$-wire <br> - Optional redundant signal <br> - CANopen ${ }^{\circledR}$ <br> Protocol in accordance with $\mathrm{CiA}^{\circledR} 301$, device profile $\mathrm{CiA}^{\circledR} 404$, communication services LSS $\left(\mathrm{CiA}^{\circledR} 305\right)$, configuration of the instrument address and baud rate Sync/Async, Node/Lifeguarding, heartbeat; zero and span $\pm 10$ \% adjustable via entries in the object directory ${ }^{2)}$ |
| Current/power consumption | Current output: $4 \ldots 20 \mathrm{~mA}$, Signal current: 2 -wire |
| Supply voltage UB | DC $10 \ldots 30 \mathrm{~V}$ for current output |
| Load | $\leq(\mathrm{UB}-10 \mathrm{~V}) / 0.024 \mathrm{~A}$ for current output |
| Response time | $<1 \mathrm{~ms}\left(\text { within } 10 \% \text { to } 90 \% \mathrm{~F}_{\text {nom }}\right)^{3}$ ) |
| Ingress protection (per EN/IEC 60529) |  |
| Unplugged state | IP66, IP67 |
| Plugged-in state | IP68, IP69, IP69K |
| Electrical protection | Reverse polarity protection, overvoltage and short-circuit resistance |
| Vibration resistance) | $20 \mathrm{~g}, 100 \mathrm{~h}, 50 \ldots 150 \mathrm{~Hz}$ (per DIN EN 60068-2-6) |
| Immunity | - Per DIN EN 61326-1/DIN EN 61326-2-3 <br> - EMC-strengthened versions |
| Intended use | Indoor and outdoor use, typically at altitudes of up to 2,500 m [8,202.5 ft] above sea level. |

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## Approvals

| Logo | Description | Region |
| :--- | :--- | :--- |
| CE | EU declaration of conformity <br> EMC directive | European Union |

Optional approvals

| Logo | Description | Region |
| :--- | :--- | :--- |
| EH[ | EAC | EMC directive |

$\rightarrow$ Approvals and certificates, see website

## Dimensions in mm [in]

## Version up to 30 kN [6,744 lbf], female thread



Version from 45 kN [10,116 lbf] male thread


| Rated force in $k N$ | Dimensions in mm |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | A | B | C | ØС | $\begin{gathered} \varnothing D 1 \\ -0.008 \end{gathered}$ | ØD2 | E | F | G | GL | H | J1 | J2 | ØK |
| 10 | 34 | 24 | 25.3 | - | 12- | 14.9 | 10 | 35 | M12 | 18 | 31 | 56 | 76 | 17.5 |
| 20 | 46 | 26 | 25.3 | - | 17 | 20.7 | 14 | 46 | M20 $\times 1.5$ | 30 | 35 | 56 | 76 | 31 |
| 30 | 46 | 27 | 26 | - | 17 | 20.7 | 14 | 46 | M20 $\times 1.5$ | 30 | 40 | 56.5 | 76.5 | 31 |
| 45 | 53 | - | - | 38 | 20 | 24.2 | 16 | 54 | M24 $\times 2$ | 36 | 50 | 58 | 78 | 35 |


| Rated force in kN | Dimensions in mm |  |  |  |  |  |  | Tightening torque MA (Nm) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | L1 | L2 | L3 | M | U | SW | Rated displacement |  |
| 10 | 105 | 88 | 31 | 8 | 13 | 19 | < 0.02 | 15 |
| 20 | 133 | 110 | 44 | 11 | 20 | 19 | $<0.2$ | 60 |
| 30 | 138 | 115 | 44 | 11 | 20 | 19 | $<0.2$ | 60 |
| 45 | 166 | 139.5 | 53 | 13 | 30 | 19 | $<0.2$ | 110 |


| Rated force in lbf | Dimensions in inch |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | A | B | C | ØC | $\begin{aligned} & \text { ØD1 } \\ & -0.0003 \end{aligned}$ | ØD2 | E | F | G | GL | H | J1 | J2 | ØK |
| 2,248 | 1.34 | 0.94 | 1 | - | 0.47 | 0.587 | 0.39 | 1.38 | M12 | 0.71 | 1.22 | 2.20 | 2.99 | 0.69 |
| 4,496 | 1.81 | 1.02 | 1 | - | 0.67 | 0.81 | 0.55 | 1.81 | M20 $\times 1.5$ | 1.18 | 1.38 | 2.20 | 2.99 | 1.22 |
| 6,744 | 1.81 | 1.06 | 1.02 | - | 0.67 | 0.81 | 0.55 | 1.81 | M20 $\times 1.5$ | 1.18 | 1.57 | 2.22 | 3.01 | 1.22 |
| 10,116 | 2.09 | - | - | 1.5 | 0.79 | 0.95 | 0.63 | 2.13 | M $24 \times 2$ | 1.42 | 1.97 | 2.28 | 3.07 | 1.38 |


| Rated force <br> in Ibf | Dimensions in inch |  |  | Tightening torque MA |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\left(\begin{array}{ll}\text { Nm }\end{array}\right.$ |  |  |  |  |  |  |  |  |
| $\mathbf{2 , 2 4 8}$ | 4.13 | 3.46 | 1.22 | 0.31 | 0.51 | 0.75 | $<0.0008$ | 15 |
| $\mathbf{4 , 4 9 6}$ | 5.24 | 4.33 | 1.73 | 0.43 | 0.79 | 0.75 | $<0.0079$ | 60 |
| $\mathbf{6 , 7 4 4}$ | 5.43 | 4.53 | 1.73 | 0.43 | 0.79 | 0.75 | $<0.0079$ | 60 |
| $\mathbf{1 0 , 1 1 6}$ | 6.54 | 5.49 | 2.09 | 0.51 | 1.18 | 0.75 | $<0.0079$ | 110 |

## Dimensions in mm [in]

Version up to 30 kN [6,744 lbf], male thread


Version from 45 kN [10,116 lbf], male thread


| Rated force in $k N$ | Dimensions in mm |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | A | B | C | ØС | $\begin{gathered} \hline \varnothing D 1 \\ -0.008 \end{gathered}$ | ØD2 | E | F | G | H | J1 | J2 |
| 10 | 34 | 24 | 25.3 | - | 14.9 | 12 | 10 | 35 | M12 | 31 | 56 | 76 |
| 20 | 46 | 26 | 25.3 | - | 20.7 | 17 | 14 | 46 | M20 $\times 1.5$ | 35 | 56 | 76 |
| 30 | 46 | 27 | 26 | - | 20.7 | 17 | 14 | 46 | M $20 \times 1.5$ | 44 | 56.5 | 76.5 |
| 45 | 53 | - | - | 38 | 24.2 | 20 | 16 | 54 | M $24 \times 2$ | 50 | 58 | 78 |


| Rated force in $k N$ | Dimensions in mm |  |  |  |  |  | Tightening torque MA (Nm) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | L1 | L2 | L3 | M | N | Rated displacement |  |
| 10 | 97 | 80 | 23 | 8 | 6 | < 0.02 | 15 |
| 20 | 123 | 100 | 34 | 11 | 10 | $<0.2$ | 60 |
| 30 | 132 | 109 | 34 | 11 | 10 | $<0.2$ | 60 |
| 45 | 153 | 126.5 | 40 | 13 | 12 | $<0.2$ | 110 |


| Rated force in lbf | Dimensions in inch |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | A | B | C | ØС | $\begin{array}{\|c\|} \hline \text { ØD1 } \\ -0.0003 \end{array}$ | ØD2 | E | F | G | H | J1 | J2 |
| 2,248 | 1.34 | 0.94 | 1 | - | 0.47 | 0.587 | 0.39 | 1.38 | M12 | 1.22 | 2.20 | 2.99 |
| 4,496 | 1.81 | 1.02 | 1 | - | 0.67 | 0.81 | 0.55 | 1.81 | M $20 \times 1.5$ | 1.38 | 2.20 | 2.99 |
| 6,744 | 1.81 | 1.06 | 1.02 | - | 0.67 | 0.81 | 0.55 | 1.81 | M $20 \times 1.5$ | 1.73 | 2.22 | 3.01 |
| 10,116 | 2.09 | - | - | 1.5 | 0.79 | 0.95 | 0.63 | 2.13 | M $24 \times 2$ | 1.97 | 2.28 | 3.07 |


| Rated force in lbf | Dimensions in inch |  |  |  |  |  | Tightening torque MA (Nm) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | L1 | L2 | L3 | M | N | Rated displacement |  |
| 2,248 | 3.82 | 3.15 | 0.91 | 0.31 | 0.24 | < 0.0008 | 15 |
| 4,496 | 4.84 | 3.94 | 1.34 | 0.43 | 0.39 | < 0.0079 | 60 |
| 6,744 | 5.20 | 4.29 | 1.34 | 0.43 | 0.39 | < 0.0079 | 60 |
| 10,116 | 6.02 | 4.98 | 1.57 | 0.51 | 0.47 | < 0.0079 | 110 |

## Pin assignment of analogue output

Abbreviations, definitions

| Signal | Description |
| :--- | :--- |
| UB | Voltage source for sensor |
| UB+ | Sensor-supply voltage ( + ) |
| UB- | Sensor-supply voltage ( - ) |
| UR | Voltage source for den signal jump |
| UR+ | Signal jump-supply voltage $(+)$ |
| UR- | Signal jump-supply voltage $(-)$ |
| S+ | Output signal ( + ) |
| S- | Output signal $(-)$ |
| OV | OV-Potential |


| Signal | Description |
| :--- | :--- |
| A) | Ammeter |
| (V) | Voltmeter |
| + | Voltage source |
| $\nearrow-$ | Switch |
| $\left({ }_{-}^{+}\right.$ | Shield [grounding] |

Output 4 ... 20 mA, 2-wire
Connector M12 x 1, 5-pin


Output 4 ... 20 mA, 3-wire
Connector M12 x 1, 5-pin


Output 0 ... 10 V, 3-wire
Connector M12 x 1, 5-pin


## Pin assignment with signal jump

Output 4 ... 20 mA, 2-wire
Circular connector M12 x 1, 4-pin


| Signal | $\mathbf{4}$.. $\mathbf{2 0} \mathbf{~ m A , ~ 2 - w i r e ~}$ | Cable colour |
| :--- | :--- | :--- |
| UB+/S+ | 1 | Brown |
| OV/S- | 3 | Black |
| Shield $\boldsymbol{F}$ | Case $/$ connector | - |

Cable colours are only valid when using the standard WIKA cable, e.g. order number: 14259454

| Signal | $\mathbf{4} \ldots \mathbf{\text { 20 mA, 3-wire }}$ | Cable colour |
| :--- | :--- | :--- |
| UB+ | 1 | Brown |
| S+ | 4 | Black |
| OV/S- | 3 | Blue |
| Shield $\boldsymbol{-}$ ) | Case / connector | - |

Cable colours are only valid when using the standard WIKA cable, e.g. order number: 14259454

| Signal | $0 \ldots \mathbf{1 0}$ V, 3-wire | Cable colour |
| :--- | :--- | :--- |
| UB+ | 1 | Brown |
| S+ | 4 | Black |
| OV/S- | 3 | Blue |
| Shield $\#$ | Case / connector | - |

Cable colours are only valid when using the standard WIKA cable, e.g. order number: 14259454

| Signal | 4 ... 20 mA, 2-wire | Cable colour |
| :---: | :---: | :---: |
| UB+/S+ | 1 | Brown |
| OV/S- | 3 | Blue |
| UR+ | 2 | White |
| UR- | 4 | Black |
| Shield $\xlongequal{( })$ | Case / connector | - |

Cable colours are only valid when using the standard WIKA cable, e.g. order number: 14259454

## Pin assignment with signal jump

Output 4 ... 20 mA, 3-wire
Circular connector M12 x 1, 4-pin


| Signal | 4 ... 20 mA, 3-wire | Cable colour |
| :---: | :---: | :---: |
| UB+ | 1 | Brown |
| OV/S- | 3 | Blue |
| UR+ | 2 | White |
| UR- | 3 | Blue |
| S+ | 4 | Black |
| Shield $\uparrow$ | Case / connector | - |

Cable colours are only valid when using the standard WIKA cable, e.g. order number: 14259454

Output 0 ... 10 V , 3-wire
Circular connector M12 x 1, 4-pin


| Signal | $\mathbf{0}$... 10 V, 3-wire | Cable colour |
| :--- | :--- | :--- |
| UB+ | 1 | Brown |
| OV/S- | 3 | Blue |
| UR+ | 2 | White |
| UR- | 3 | Blue |
| S+ | 4 | Black |
| Shield $\boldsymbol{-}$ | Case / connector | - |

Cable colours are only valid when using the standard WIKA cable, e.g. order number: 14259454

## Pin assignment redundant with $1 \times$ connector

Abbreviations, definitions

| Signal | Description |
| :--- | :--- |
| UB | Voltage source for the sensor |
| UB+ | Sensor voltage supply (+) |
| UB- | Sensor voltage supply $(-)$ |
| S+ | Output signal $(+)$ |
| S- | Output signal $(-)$ |
| CH1 | Channel 1 |
| CH2 | Channel 2 |
| CH1+2 | Channel 1 and channel 2 |
| $\mathbf{0 V}$ | OV potential |


| Signal | Description |
| :--- | :--- |
| A | Ammeter |
| ( | Voltmeter |
| $\pm$ | Voltage source |
| $\nearrow-$ | Switch |
| $(\underset{)}{ }$ | Shield [ground] |

Output 4 ... 20 mA, 2-wire
Circular connector M12 x 1, 5-pin


| Signal | $\mathbf{4}$... $\mathbf{2 0}$ mA, 2-wire | Cable colour |
| :--- | :--- | :--- |
| UB+/S+ (CH1) | 1 | Brown |
| UB+/S+ (CH2) | 2 | White |
| OV/S- (CH1) | 3 | Blue |
| OV/S- (CH2) | 4 | Black |
| Shield $\boldsymbol{1}$ ) | Case / Connector | - |

Cable colours are only valid when using the standard WIKA cable, e.g. order number: 14259454

## Pin assignment redundant with $1 \times$ connector

Output 4 ... 20 mA, 3-wire
Circular connector M12 x 1, 5-pin


| Signal | $\mathbf{4}$... $\mathbf{2 0} \mathbf{~ m A , ~ 3 - w i r e ~}$ | Cable colour |
| :--- | :--- | :--- |
| UB+ (CH1+2) | 1 | Brown |
| OV/S- (CH1+2) | 3 | Blue |
| S+(CH1) | 4 | Black |
| S+ (CH2) | 2 | White |
| Shield () | Case / connector | - |

Cable colours are only valid when using the standard WIKA cable, e.g. order number: 14259454

| Signal | $\mathbf{0} \ldots \mathbf{1 0}$ V, 3-wire | Cable colour |
| :--- | :--- | :--- |
| UB+ (CH1+2) | 1 | Brown |
| OV/S- (CH1+2) | 3 | Blue |
| S+(CH1) | 4 | Black |
| S+ (CH2) | 2 | White |
| Shield $\boldsymbol{=})$ | Case $/$ connector | - |

Cable colours are only valid when using the standard WIKA cable, e.g. order number: 14259454

## Pin assignment for CANopen ${ }^{\circledR}$ in according to $\mathrm{CiA}^{\circledR 303-1}$

Abbreviations, definitions

| Signal | Description |
| :--- | :--- |
| CAN-SHLD, Shield $\mathcal{F}$ | Shield |
| CAN-V+ | External positive voltage supply for the supply of the sensor |
| CAN-GND | External OV Potential for the supply of the sensor |
| CAN-High | CAN_H Bus line (dominant high) |
| CAN-Low | CAN_L Bus line (dominant low) |

Output CANopen ${ }^{\circledR}$
Circular connector M12 x 1, 5-pin


| Signal | Pin | Cable colour |
| :--- | :--- | :--- |
| CAN-SHLD, shield $\Theta$ | $1 /$ case / connector | Brown |
| CAN-V+ | 2 | Blue |
| CAN-GND | 3 | White |
| CAN-High | 4 | Blue |
| CAN-Low | 5 | Black |

Cable colours are only valid when using the standard WIKA cable, e.g. order number: 14259454

## Short description of the signal jump electronics

Amplifier $4 \ldots 20 \mathrm{~mA}$ or $0 \ldots 10 \mathrm{~V}$ for signal jump applications with 2-channel computer control.


With these force transducers, four variable resistors (R1 ... R4) are connected together to form a Wheatstone bridge. When the measuring body deforms, the opposing resistors are stretched or compressed in the same way. This leads to a detuning of the bridge and a diagonal voltage U0.

The test resistor R7 is now important in connection with checking the subsequent amplifier circuit and the subsequent signal paths. This is switched parallel to the resistor R5 via the relay contact (a) as soon as the excitation voltage Ur of the relay $A$ is present. The connection of the resistor R7 causes a defined, always constant, detuning of the zero point (diagonal voltage) of the Wheatstone bridge.

An external controller that is independent of the force transducer must monitor the safe functioning of the force transducer. The functional test with a signal jump of $4 \mathrm{~mA} / 2 \mathrm{~V}$ is executed at an interval of 24 hours. The controller activates the relay A , thus changing the output signal of the force transducer in a defined manner.

If the expected change in the output signal occurs, it can be assumed that the entire signal path from the Wheatstone bridge per the amplifier through to the output is functioning correctly. If no signal change occurs, then it can be concluded that there is an error in the signal path.

Furthermore, the measuring signal should be checked by the controller for min. (A) and max. (B) signal values in order to detect any cable breaks or short circuits that may occur.

The default setting of the force transducers with a current output of $4 \ldots 20 \mathrm{~mA}$ for overload detection is, for example:


Signals of the signal jump electronics
With a fixed signal jump of, for example, 4 mA , the test cycle can then be triggered, in any operating state, by activating the test relay. The upper measuring range limit of 20 mA will never be reached and thus the checking of the signal jump is enabled.

Accessories
Connectors model EZE53 with moulded cable

| Model | Description | Temperature range | Cable diameter | Cable length | Order number |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Straight version, cut to length, 4-pin, PUR cable, UL listed, IP67 | $\begin{aligned} & -20 \ldots+80^{\circ} \mathrm{C} \\ & {\left[-4 \ldots+176{ }^{\circ} \mathrm{F}\right]} \end{aligned}$ | $\begin{aligned} & 4.75 \mathrm{~mm} \ldots 5.7 \mathrm{~mm} \\ & {[0.18 \mathrm{in} \ldots 0.22 \mathrm{in}]} \end{aligned}$ | $2 \mathrm{~m}[6.6 \mathrm{ft}]$ | 14259451 14259453 |
|  |  |  |  | 5 m [16.4 ft] | 14259453 |
|  |  |  |  | 10 m [32.8 ft] | 14259454 |
|  | Straight version, cut to length, 5-pin, PUR cable, UL listed, IP67 | $\begin{aligned} & -20 \ldots+80^{\circ} \mathrm{C} \\ & {\left[-4 \ldots+176{ }^{\circ} \mathrm{F}\right]} \end{aligned}$ | $\begin{aligned} & 4.75 \mathrm{~mm} \ldots 5.7 \mathrm{~mm} \\ & {[0.18 \mathrm{in} \ldots 0.22 \mathrm{in}]} \end{aligned}$ | 2 m [6.6 ft] | 14259458 |
|  |  |  |  | 5 m [16.4 ft] | 79100672 |
|  |  |  |  | 10 m [32.8 ft] | 14259472 |
|  | Angled version, cut to length, 4-pin, PUR cable, UL listed, IP67 | $\begin{aligned} & -20 \ldots+80^{\circ} \mathrm{C} \\ & {\left[-4 \ldots+176{ }^{\circ} \mathrm{F}\right]} \end{aligned}$ | $\begin{aligned} & 5.05 \mathrm{~mm} \ldots 6 \mathrm{~mm} \\ & {[0.2 \mathrm{in} \ldots 0.24 \mathrm{in}]} \end{aligned}$ | 2 m [6.6 ft] | 14259452 |
|  |  |  |  | 5 m [16.4 ft] | 14293481 |
|  |  |  |  | 10 m [32.8 ft] | 14259455 |
|  | Angled version, cut to length, 5-pin, PUR cable, UL listed, IP67 | $\begin{aligned} & -20 \ldots+80^{\circ} \mathrm{C} \\ & {\left[-4 \ldots+176{ }^{\circ} \mathrm{F}\right]} \end{aligned}$ | $5.05 \mathrm{~mm} \ldots 6 \mathrm{~mm}$ $[0.2 \mathrm{in} \ldots 0.24 \mathrm{in}]$ <br> [ 0.2 in ... 0.24 in ] | 2 m [6.6 ft] | 79101493 |
|  |  |  |  | 5 m [16.4 ft] | 79100686 |
|  |  |  |  | 10 m [32.8 ft] | On request |

Further cable lengths and cable types are available on request.
$\rightarrow$ WIKA accessories can be found online at www.wika.com.

## Ordering information

Model / Rated force / Relative linearity error / Temperature range / Output signal / Electrical connection / Approvals, certificates / Pin assignment / Accessories

[^1]
## WIKA]

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[^0]:    1) Relative linearity error is specified in accordance with Directive VDI/VDE/DKD 2638 chapter 3.2.6.
    2) Protocol in accordance with $\mathrm{CiA}^{\circledR 301, ~ d e v i c e ~ p r o f i l e ~} \mathrm{CiA}^{\circledR} 404$, communication service LSS ( $\mathrm{CiA}^{\circledR 3} 305$ )
    3) Other response times possible upon request.

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    In case of a different interpretation of the translated and the English data sheet, the English wording shall prevail.

